Electronic Journal of Differential Equations, Vol. 2008(2008), No. 118, pp. 1–14. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu ftp ejde.math.txstate.edu (login: ftp)

AMBROSETTI-PRODI TYPE RESULTS IN A SYSTEM OF SECOND AND FOURTH-ORDER ORDINARY DIFFERENTIAL EQUATIONS

YUKUN AN, JING FENG

ABSTRACT. In this paper, by the variational method, we study the existence, nonexistence, and multiplicity of solutions of an Ambrosetti-Prodi type problem for a system of second and fourth order ordinary differential equations.

1. INTRODUCTION

Lazer and McKenna [1] presented the following (one-dimensional) mathematical model for the suspension bridge:

$$y_{tt} + y_{xxxx} + \delta_1 y_t + k(y-z)^+ = W(x), \quad \text{in } (0,L) \times \mathbb{R},$$

$$z_{tt} - z_{xx} + \delta_2 z_t - k(y-z)^+ = h(x,t), \quad \text{in } (0,L) \times \mathbb{R},$$

$$y(0,t) = y(L,t) = y_{xx}(0,t) = y_{xx}(L,t) = 0, \quad t \in \mathbb{R},$$

$$z(0,t) = z(L,t) = 0, \quad t \in \mathbb{R}.$$
(1.1)

Where the variable z measures the displacement from equilibrium of the cable and the variable y measures the displacement of the road bed. The constant k is spring constant of the ties.

When the motion of the cable is ignored, the coupled system (1.1) can be simplified into a single equation which describes the motion of the road bed of suspension bridge, as follows

$$y_{tt} + y_{xxxx} + \delta y_t + ky^+ = W(x,t), \quad \text{in } (0,L) \times \mathbb{R}, y(0,t) = y(L,t) = y_{xx}(0,t) = y_{xx}(L,t) = 0, \quad t \in \mathbb{R}.$$
(1.2)

This Problem have been studied by many authors. In [2, 3, 4], the authors, using degree theory and the variational method, investigated the multiplicity of some symmetrical periodic solutions when $\delta = 0$ and $W(x,t) = 1 + \epsilon h(x,t)$ or $W(x,t) = \alpha \cos x + \beta \cos 2t \cos x\epsilon$. In [5], the similar results for (1.2) are obtained in case of $\delta \neq 0$ and $W(x,t) = h(x,t) = \alpha \cos x + \beta \cos 2t \cos x + \gamma \sin 2t \cos x$. Those results give the conditions impose on the spring constant k which guarantees the existence of multiple periodic solutions, especially the sign-changing periodic

²⁰⁰⁰ Mathematics Subject Classification. 34B08, 34B15, 34L30, 47J30.

Key words and phrases. Differential system; Ambrosetti-Prodi type problem; subsolution; supersolution; variational method.

^{©2008} Texas State University - San Marcos.

Submitted March 17, 2008. Published August 25, 2008.

solutions in the case of W(x,t) is single-sign. It is notable that the functions $\cos x, \cos 2t \cos x, \sin 2t \cos x$ are the eigenfunctions of linear principal operator of (1.2) in some function spaces.

When we consider only the steady state solutions of problem (1.1), we arrive at the system

$$y_{xxxx} + k(y-z)^{+} = h_{1}(x), \quad \text{in } (0,\pi),$$

$$-z_{xx} - k(y-z)^{+} = h_{2}(x), \quad \text{in } (0,\pi),$$

$$y(0) = y(\pi) = y_{xx}(0) = y_{xx}(\pi) = 0,$$

$$z(0) = z(\pi) = 0.$$

(1.3)

This problem has little been studied in [12, 13]. In [6, 15], the analogous partial differential systems have been considered when the nonlinearities $k(y-z)^+$, $-k(y-z)^+$ are replaced by general $f_1(y, z), f_2(y, z)$. And also, in recently, literature [16] studied the system

$$y_{xx} + k_1 y^+ + \epsilon z^+ = \sin x, \quad \text{in } (0, \pi),$$

$$z_{xx} + \epsilon y^+ + k_2 z^+ = \sin x, \quad \text{in } (0, \pi),$$

$$y(0) = y(\pi) = 0,$$

$$z(0) = z(\pi) = 0.$$

(1.4)

Where $u^+ = \max\{u, 0\}$, the constant ϵ is small enough such that the matrix

$$\begin{pmatrix} k_1 & \epsilon \\ \epsilon & k_2 \end{pmatrix}$$

is a near-diagonal matrix and the positive numbers k_1, k_2 satisfy

$$m_1^2 < k_1 < (m_1 + 1)^2, \ m_2^2 < k_2 < (m_2 + 1)^2 \text{ for some } m_1, m_2 \in \mathbf{N}.$$

This is a first work in the direction of extending to systems some of well-known results established on nonlinear equation with an asymmetric nonlinearity. Meanwhile in [16] there are two open questions to be interesting:

Question 1. Can one obtain corresponding results if the second-order differential operator is replaced with a fourth-order differential operator with corresponding boundary conditions?

Question 2. Can one replace the near-diagonal matrix with something more general and use information on the eigenvalues of matrix?

Following the above works and questions, we consider the system

$$-u'' = f_1(x, u, v) + t_1 \sin x + h_1(x), \quad \text{in } (0, \pi)$$

$$v'''' = f_2(x, u, v) + t_2 \sin x + h_2(x), \quad \text{in } (0, \pi)$$

$$u(0) = u(\pi) = 0,$$

$$v(0) = v(\pi) = v''(0) = v''(\pi) = 0,$$

(1.5)

where t_1, t_2 are parameters and $(f_1, f_2) : [0, \pi] \times \mathbb{R}^2 \to \mathbb{R}^2$ is asymptotically linear. On the other hand, the second order elliptic systems as follows

$$-\Delta u = f_1(u, v) + t_1\varphi_1 + h_1(x), \quad \text{in } \Omega,$$

$$-\Delta v = f_2(u, v) + t_2\varphi_1 + h_2(x), \quad \text{in } \Omega,$$

$$u = v = 0, \quad \text{on } \partial\Omega$$
(1.6)

have been widely studied. Here we mention the papers [7, 8, 9, 10] and the references therein. If $(f_1, f_2) : \mathbb{R}^2 \to \mathbb{R}^2$ is asymptotically linear and the asymptotic matrixes at $-\infty$ and $+\infty$ are

$$\begin{pmatrix} \underline{a} & \underline{b} \\ \underline{c} & \underline{d} \end{pmatrix}, \quad \begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix}$$

Under some growth conditions on (f_1, f_2) , in those papers, the Ambrosetti-Prodi type results for (1.6) have been given respectively.

We remind that let $g \in C^{\alpha}(\overline{\Omega} \times \mathbb{R})$ be a given function such that

$$\limsup_{s \to -\infty} \frac{g(x,s)}{s} < \lambda_1 < \liminf_{s \to +\infty} \frac{g(x,s)}{s}$$

uniformly in $x \in \Omega$, where λ_1 is the first eigenvalue of the Laplacian on a bounded domain Ω under the Dirichlet condition and φ_1 is the associated eigenfunction. The Ambrosetti-Prodi type result in a Cartesian version states that for a given $h \in C^{\alpha}(\overline{\Omega})$ there exists a real number t_0 such that the problem

$$-\Delta u = g(x, u) + t\varphi_1 + h, \quad \text{in } \Omega$$
$$u = 0, \quad \text{on } \partial \Omega$$

(i) has no solution if $t > t_0$;

(ii) has at least two solutions if $t < t_0$.

With different variants and formulations this problem has been extensively studied.

Inspired, we consider the Ambrosetti-Prodi type problem for system (1.5). This paper is organized as follows: in Section 2, we prepare the proper variational framework and prove (PS) condition to the Euler-Lagrange functional associated to our problem. In Section 3, we prove the main theorem. Finally, a piecewise linear problem is considered as an example in Section 4.

2. Preliminaries

In this section, we prepare the proper variational frame work for (1.5), that is

$$-u'' = f_1(x, u, v) + t_1 \sin x + h_1(x), \quad \text{in } (0, \pi)$$
$$v'''' = f_2(x, u, v) + t_2 \sin x + h_2(x), \quad \text{in } (0, \pi)$$
$$u(0) = u(\pi) = 0,$$
$$v(0) = v(\pi) = v''(0) = v''(\pi) = 0.$$

Where t_1, t_2 are parameters, $h_1, h_2 \in C[0, \pi]$ are fixed functions with $\int_0^{\pi} h_1 \sin x = \int_0^{\pi} h_2 \sin x = 0$.

We shall need some assumptions on the nonlinearities, which are necessary to settle the existence or not of solutions in the case of the Ambrosetti-Prodi type problem and to establish (PS) condition.

Let us order \mathbb{R}^2 with the order defined by

$$\xi = (\xi_1, \xi_2) \ge 0 \Longleftrightarrow \xi_1, \xi_2 \ge 0.$$

and denote W = (u, v) and $F(x, W) = (f_1(x, u, v), f_2(x, u, v)).$

We will use the following hypotheses in this article.

(H1) $F = (f_1, f_2) : [0, \pi] \times \mathbb{R}^2 \to \mathbb{R}^2$ is locally Lipschitzian function respect to u, v, and there exists a function $H : [0, \pi] \times \mathbb{R}^2 \to \mathbb{R}$ such that

$$\nabla H(x, u, v) = \left(\frac{\partial H}{\partial u}, \frac{\partial H}{\partial v}\right) = (f_1(x, u, v), f_2(x, u, v)).$$

(H2) For $\xi = (\xi_1, \xi_2) > 0$ large enough,

$$F(x,\xi) \ge 0. \tag{2.1}$$

(H3) F satisfies

$$|F(x,\xi)| \le c(|\xi_1| + |\xi_2| + 1), \quad \forall \xi \in \mathbb{R}^2, \ x \in (0,\pi)$$
(2.2)

where c > 0 is constant.

(H4) For $\xi = (\xi_1, \xi_2) \in \mathbb{R}^2$ and $x \in (0, \pi)$ there holds

$$F(x,\xi) \ge \underline{A}\xi - ce, \tag{2.3}$$

for some constant c > 0. Where e = (1, 1) and the matrix $\underline{A} = \begin{pmatrix} \underline{a} & \underline{b} \\ \underline{c} & \underline{d} \end{pmatrix}$ satisfies

$$\underline{b}, \underline{c} \ge 0, \tag{2.4}$$

$$(\underline{A}\xi,\xi) \le \underline{\mu}|\xi|^2, \quad \text{for some } 0 < \underline{\mu} < 1.$$
(2.5)

(H5) For $\xi = (\xi_1, \xi_2) \in \mathbb{R}^2$ and $x \in (0, \pi)$ there holds

$$F(x,\xi) \ge \overline{A}\xi - ce, \tag{2.6}$$

for some constant c > 0. Where e = (1, 1) and the matrix $\overline{A} = \begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix}$ satisfies

$$\overline{b}, \overline{c} \le 0, \tag{2.7}$$

$$(\overline{A}\xi,\xi) \ge \overline{\mu}|\xi|^2$$
, for some $\overline{\mu} > 1$. (2.8)

(If not mentioned, c will always denote a generic positive constant.)

Remark 2.1. With a simple computation it is easy to show that (2.4)-(2.5) and (2.7)-(2.8) imply, respectively,

$$(1 - \underline{a})(1 - \underline{d}) - \underline{bc} > 0, \quad \underline{a}, \underline{d} < 1,$$

$$(\underline{A} - I)^{-1} \xi \le 0, \quad \forall \xi \in \mathbb{R}^2, \ \xi \ge 0,$$
(2.9)

and

$$(1-\overline{a})(1-\overline{d}) - \overline{b}\overline{c} > 0, \quad \overline{a}, \overline{d} > 1, (\overline{A}-I)^{-1}\xi \ge 0, \quad \forall \xi \in \mathbb{R}^2, \ \xi \ge 0,$$

$$(2.10)$$

where I is the identity matrix.

Let
$$X = H_0^1(0,\pi) \times (H_0^1(0,\pi) \cap H^2(0,\pi))$$
 be Hilbert space with the inner product
 $\langle W, \Psi \rangle = \int_0^{\pi} (u'\psi_1' + v''\psi_2''), \quad \forall W = (u,v), \ \Psi = (\psi_1,\psi_2) \in X,$

and the corresponding norm

$$||W||_X^2 = \int_0^{\pi} ({u'}^2 + {v''}^2).$$

Consider the second-order ordinary differential eigenvalue problem

$$-u'' = \lambda u, \quad \text{in } (0, \pi),$$

 $u(0) = u(\pi) = 0,$

and the fourth-order ordinary differential eigenvalue problem

$$v'''' = \lambda v, \text{ in } (0, \pi),$$

 $v(0) = v(\pi) = v''(0) = v''(\pi) = 0.$

It is well known that $\lambda_1 = 1$ and $\varphi_1 = \sin x$ are the positive first eigenvalue and the associated eigenfunction, respectively. Hence, it follows from the Poincare inequality that, for all $W \in X$,

$$\int_0^\pi |W|^2 \le ||W||_X^2. \tag{2.11}$$

A vector $W \in X$ is a weak solution of (1.5) if, and only if, it is a critical point of the associated Euler-Lagrange functional

$$J(W) = \frac{1}{2} \int_0^{\pi} ({u'}^2 + {v''}^2) - \int_0^{\pi} H(x, u, v) - \int_0^{\pi} [(t_1 \sin x + h_1)u + (t_2 \sin x + h_2)v]$$
(2.12)

It is standard to show that the functional J(W) is well defined, $J(W) \in C^1(X, \mathbb{R})$ and $X \to \mathbb{R}$; $W \to \int_0^{\pi} H(x, u, v) + \int_0^{\pi} [(t_1 \sin x + h_1)u + (t_2 \sin x + h_2)v]$ has compact derivative under the assumptions (H1) and (H3).

Lemma 2.2. Assume that (H1)-(H5) hold. Then J satisfies the (PS) condition.

Proof. Let $\{W_n = (u_n, v_n)\} \subset X$ be a sequence such that $|J(W_n)| \leq c$ and $J'(W_n) \to 0$. This implies

$$\left| \int_{0}^{\pi} (u'_{n}\psi'_{1} + v''_{n}\psi''_{2}) - \int_{0}^{\pi} \left[(f_{1}\psi_{1} + f_{2}\psi_{2}) + (t_{1}\sin x + h_{1})\psi_{1} + (t_{2}\sin x + h_{2})\psi_{2} \right] \right| \\ \leq \varepsilon_{n} \|\Psi\|_{X}$$
(2.13)

for all $\Psi = (\psi_1, \psi_2) \in X$, where $\varepsilon_n \to 0 (n \to \infty)$. Then by the above discussion it suffices to prove that $\{W_n\}$ is bounded.

Step 1: Show the boundedness of $\{W_n^-\}$. Let $W_n^- = (u_n^-, v_n^-), w^- = \max\{0, -w\}$. Since h_1, h_2 are bounded, there exists $M_1, M_2 \ge 0$ such that

$$|t_1 \sin x + h_1| \le M_1, \quad |t_2 \sin x + h_2| \le M_2. \tag{2.14}$$

Moreover, from (2.3) and (2.4), we have

$$f_1(x, u_n, v_n)(-u_n^-) \le \underline{a}(u_n^-)^2 + \underline{b}u_n^- v_n^- + cu_n^-, f_2(x, u_n, v_n)(-v_n^-) \le \underline{d}(v_n^-)^2 + \underline{c}u_n^- v_n^- + cv_n^-.$$

Choosing $c > \max\{M_1, M_2\}$ and taking $\psi_1 = -u_n^-, \psi_2 = -v_n^-$ in (2.13), then using the above inequalities and (2.5), we obtain

$$\begin{split} \|W_n^-\|_X^2 &\leq \int_0^{\pi} (\underline{A}W_n^-, W_n^-) + \int_0^{\pi} (cu_n^- - M_1 u_n^- + cv_n^- - M_2 v_n^-) + c \|W_n^-\|_X \\ &\leq \underline{\mu} \int_0^{\pi} |W_n^-|^2 + d \int_0^{\pi} (u_n^- + v_n^-) + c \|W_n^-\|_X. \end{split}$$

Where $d \ge \max\{c - M_1, c - M_2\}$ is constant. Using Hölder inequality and Poincare inequality, we get

$$\begin{split} &\int_0^\pi |u_n^-| \leq c (\int_0^\pi |u_n^-|^2)^{1/2} \leq c (\int_0^\pi |u_n^-'|^2)^{1/2}, \\ &\int_0^\pi |v_n^-| \leq c (\int_0^\pi |v_n^-|^2)^{1/2} \leq c (\int_0^\pi |v_n^{-\prime\prime}|^2)^{1/2}. \end{split}$$

Then from these two inequalities and (2.11) we have

$$(1-\mu)\|W_n^-\|_X^2 \le c\|W_n^-\|_X,$$

since $0 < \mu < 1$, $||W_n^-||$ is bounded.

Step 2: Show the boundedness of $\{W_n\}$. Suppose by contradiction that $\{W_n\}$ is unbounded, then there exists a subsequence (still denote $\{W_n\}$) such that $||W_n||_X \to \infty$ as $n \to \infty$. Setting $V_n = (x_n, y_n) = W_n / ||W_n||_X$, then $||V_n||_X = 1$ and there exists a subsequence such that

$$V_n \rightharpoonup V_0 = (x_0, y_0), \quad \text{in } X,$$
 (2.15)

$$V_n \to V_0, \quad \text{in } L^2(0,\pi) \times L^2(0,\pi),$$
 (2.16)

$$V_n \to V_0$$
, a.e. in $(0, \pi)$,

with
$$|x_n(x)|, |y_n(x)| \le h(x) \in L^2, \ x \in (0, \pi).$$
 (2.17)

By step 1 we may assume that $V_n^- \to 0$ in $L^2 \times L^2$ and $V_n^- \to 0$ a.e.in $(0, \pi)$. Clearly, $V_0 \ge 0$. Denote

$$G_n(x) = (g_n^1(x), g_n^2(x))$$

= $\frac{(f_1(x, W_n(x)) + t_1 \sin x + h_1, f_2(x, W_n(x)) + t_2 \sin x + h_2)}{\|W_n\|_X}$

We claim that

$$G_n \to \gamma = (\gamma_1, \gamma_2) \ge 0 \quad \text{in } L^2 \times L^2.$$
 (2.18)

In fact, let $A_n = \{x \in (0, \pi); u_n(x) \leq 0 \text{ and } v_n(x) \leq 0\}$ and let χ_n denotes its characteristic function, then $G_n = \chi_n G_n + (1 - \chi_n) G_n$. By (H3), (2.16), (2.17) and using the Lebesgue Dominated Convergence Theorem, we get

$$\chi_n \frac{F(x, W_n)}{\|W_n\|_X} \to 0 \quad \text{in } L^2 \times L^2.$$

Moreover, from (2.14) we have

$$\chi_n \frac{(t_1 \sin x + h_1, t_2 \sin x + h_2)}{\|W_n\|_X} \to 0 \quad \text{in } L^2 \times L^2.$$

Hence $\chi_n G_n \to 0$ in $L^2 \times L^2$. With the same reasoning $(1 - \chi_n)G_n \to \gamma' = (\gamma'_1, \gamma'_2)$ in $L^2 \times L^2$. Therefore, we only need to prove that $\gamma' \ge 0$.

(i) If
$$u_n(x) \ge 0$$
 and $v_n(x) \le 0$, since $\overline{a} > 1$, from (2.6) we have

$$(1 - \chi_n)g_n^1(x) + \overline{b}(y_n^-(x)) + \frac{c}{\|W_n\|_X} - (1 - \chi_n)\frac{t_1 \sin x + h_1}{\|W_n\|_X} \ge \overline{a}x_n^+(x) \ge 0$$

and from (2.3) and (2.4), we obtain

$$(1-\chi_n)g_n^2(x) + \underline{d}(y_n^-(x)) + \frac{c}{\|W_n\|_X} - (1-\chi_n)\frac{t_2\sin x + h_2}{\|W_n\|_X} \ge \underline{c}x_n^+(x) \ge 0$$

Since $V_n^- \to 0$ in $L^2 \times L^2$ and

$$(1 - \chi_n)g_n^1(x) + \bar{b}(y_n^-(x)) + \frac{c}{\|W_n\|_X} - (1 - \chi_n)\frac{t_1\sin x + h_1}{\|W_n\|_X} \to \gamma_1',$$

$$(1 - \chi_n)g_n^2(x) + \underline{d}(y_n^-(x)) + \frac{c}{\|W_n\|_X} - (1 - \chi_n)\frac{t_2\sin x + h_2}{\|W_n\|_X} \to \gamma_2'$$

we get $\gamma' \ge 0$.

(ii) If $u_n(x) \leq 0$ and $v_n(x) \geq 0$, we can handle in the same way to obtain that $\gamma' \geq 0$.

(iii) If $u_n(x) \ge 0$ and $v_n(x) \ge 0$, the assertion $\gamma' \ge 0$ can be inferred from (H2). Now dividing (2.13) by $||W_n||_X$, using (2.15), (2.18) and passing to the limit we obtain

$$\int_{0}^{\pi} (x_0'\psi_1' + y_0''\psi_2'') = \int_{0}^{\pi} (\gamma_1\psi_1 + \gamma_2\psi_2), \quad \forall \Psi = (\psi_1, \psi_2) \in X.$$
(2.19)

From (2.6) we have

$$\frac{(f_1(x, W_n(x)) + t_1 \sin x + h_1, f_2(x, W_n(x)) + t_2 \sin x + h_2)}{\|W_n\|_X} \ge \overline{A}V_n - \frac{ce}{\|W_n\|_X}.$$

Passing to the limit in this inequality we get

$$\gamma \ge \overline{A}V_0. \tag{2.20}$$

Taking $\psi_1 = \sin x, \psi_2 = 0$ and then $\psi_1 = 0, \psi_2 = \sin x$ in (2.19) and using (2.20), it is achieved that

$$(\overline{A} - I) \begin{pmatrix} \int_0^{\pi} x_0 \sin x \\ \int_0^{\pi} y_0 \sin x \end{pmatrix} \le 0.$$
(2.21)

From Remark 2.1, applying $(\overline{A} - I)^{-1}$ to (2.21) we get $(\int_0^{\pi} x_0 \sin x, \int_0^{\pi} y_0 \sin x) \leq 0$. Hence $x_0 = y_0 = 0$ a.e. So, from (2.19), $\int_0^{\pi} (\gamma, \Psi) = 0$ and taking $\Psi > 0$ we have $\gamma = 0$.

Finally, consider $\psi_1 = x_n, \psi_2 = y_n$ in (2.13). Dividing the resulting expression by $||W_n||_X$, and passing to the limit we obtain $1 \le 0$, that is impossible.

Lemma 2.3. Suppose (H5) hold. Then

$$\lim_{s \to +\infty} J(s \sin x, s \sin x) = -\infty.$$
(2.22)

Proof. From (2.6) we have

$$H(x, u, v) \ge \frac{\overline{a}}{2}u^2 + \overline{b}uv - cu + H(x, 0, v) \text{ as } u \ge 0, \forall v,$$
 (2.23)

$$H(x, u, v) \ge \frac{d}{2}v^2 + \bar{c}uv - cv + H(x, u, 0)$$
 as $v \ge 0, \forall u.$ (2.24)

Adding (2.23), (2.24) and using them again,

$$2H(x, u, v) \ge \frac{\overline{a}}{2}u^2 + (\overline{b} + \overline{c})uv + \frac{d}{2}v^2 - cu - cv + H(x, 0, v) + H(x, u, 0)$$

$$\ge \overline{a}u^2 + (\overline{b} + \overline{c})uv + \overline{d}v^2 - 2cu - 2cv + 2H(x, 0, 0)$$

$$\ge \overline{a}u^2 + (\overline{b} + \overline{c})uv + \overline{d}v^2 - 2cu - 2cv + 2c, \quad \text{for } u, v \ge 0.$$

Then by (2.8) we have

$$H(x,W) \ge \frac{\overline{\mu}}{2} |W|^2 - cu - cv + c.$$
 (2.25)

Taking $W = (s \sin x, s \sin x)$, where s > 0, from (2.14) and (2.25) we get

$$J(s\sin x, s\sin x) \le \frac{\pi s^2}{2} (1 - \overline{\mu}) + (c + M_1) \int_0^{\pi} s\sin x + (c + M_2) \int_0^{\pi} s\sin x - c \\ \le \frac{\pi s^2}{2} (1 - \overline{\mu}) + cs - c \\ \text{nce } \overline{\mu} > 1, \ (2.22) \text{ holds.}$$

since $\overline{\mu} > 1$, (2.22) holds.

3. The Ambrosetti-Prodi type result

In this section, we state and prove the Ambrosetti-Prodi type result for system (1.5). We need the following concepts.

Definition 3.1. (1) We say that a vector function $W \in X$ is a weak subsolution of (1.5) if $I'(W)(W) < 0 \quad \forall W \subset V \quad W > 0$

$$J(W)(\Psi) \leq 0, \quad \forall \Psi \in X, \ \Psi \geq 0.$$
(2) $W = (u, v) \in C^2 \times C^4$ is a subsolution (classical) of (1.5) if
 $-u'' \leq f_1(x, u, v) + t_1 \sin x + h_1, \quad \text{in } (0, \pi),$
 $v'''' \leq f_2(x, u, v) + t_2 \sin x + h_2, \quad \text{in } (0, \pi),$
 $u(0) = u(\pi) = 0,$
 $v(0) = v(\pi) = v''(0) = v''(\pi) = 0.$

(3) Weak supersolutions and supersolutions (classical) are defined likewise by reversing the above inequalities.

We can easily show that each a subsolution or a supersolution of (1.5) is indeed also a weak subsolution or a weak supersolution, respectively.

For to present the subsolution and supersolution for (1.5), we firstly show a maximum principle as follows.

Lemma 3.2. Let A be a matrix-function with entries in $C[0,\pi]$ satisfy (2.4) and (2.5). If $W = (u, v) \in X$ is such that

$$\int_0^{\pi} (u'\psi_1' + v''\psi_2'') \ge \int_0^{\pi} (AW, \Psi), \quad \forall \Psi = (\psi_1, \psi_2) \in X,$$
(3.1)

then $W \geq 0$.

Proof. Let $\Psi = W^- = (u^-, v^-)$ in (3.1), by (2.4) and (2.5), we obtain

$$\int_0^{\pi} (|u^{-\prime}|^2 + |v^{-\prime\prime}|^2) \le \int_0^{\pi} (AW^-, W^-) - \int_0^{\pi} (AW^+, W^-) \le \underline{\mu} \int_0^{\pi} |W^-|^2 \le \underline{\mu} ||W^-||_X^2.$$

Therefore, $W^- = 0$, i.e. $W \ge 0$.

Remark 3.3. In the classical sense, (2.4) and (2.5) are also sufficient conditions for having a maximum principle for the problem

$$-u'' = \underline{a}u + \underline{b}v + g_1(x), \quad \text{in } (0,\pi),$$

$$v'''' = \underline{c}u + \underline{d}v + g_2(x), \quad \text{in } (0,\pi),$$

$$u(0) = u(\pi) = 0,$$

This is, $W = (u, v) \ge 0$ if $g_1 \ge 0, g_2 \ge 0$.

Lemma 3.4. Assume condition (H4), i.e. (2.3), (2.4) and (2.5) hold. Then, for all $t = (t_1, t_2) \in \mathbb{R}^2$, system (1.5) has a subsolution W_t such that, if W^t is any supersolution we have

$$W_t \le W^t \quad in \ (0,\pi). \tag{3.2}$$

Proof. We consider the system

$$-u'' = \underline{a}u + \underline{b}v - c + t_1 \sin x + h_1, \quad \text{in } (0, \pi),$$

$$v'''' = \underline{c}u + \underline{d}v - c + t_2 \sin x + h_2, \quad \text{in } (0, \pi),$$

$$u(0) = u(\pi) = 0,$$

$$v(0) = v(\pi) = v''(0) = v''(\pi) = 0,$$

(3.3)

where c is the constant in (2.3) and (2.6). From the hypotheses on <u>A</u> and h_1 , h_2 , (3.3) has a unique solution $W_t \in C^2 \times C^4$. Then, using (2.3) we conclude that W_t is in fact a subsolution of (1.5).

Finally, suppose that W^t is any supersolution of (1.5), from (2.3) and applying Lemma 3.2 directly we can get the assertion (3.2).

Lemma 3.5. Suppose (H1) holds and $(h_1, h_2) \in C[0, \pi] \times C[0, \pi]$. Then there exists $t^0 \in \mathbb{R}^2$ such that, for all $t \leq t^0$, system (1.5) has a supersolution W^t .

Proof. Let $\overline{u}, \overline{v}$ be the solution of the system

$$\begin{aligned} -\overline{u}'' &= f_1(x,0,0) + h_1(x), & \text{in } (0,\pi), \\ \overline{v}'''' &= f_2(x,0,0) + h_2(x), & \text{in } (0,\pi), \\ u(0) &= u(\pi) = 0, \\ v(0) &= v(\pi) = v''(0) = v''(\pi) = 0. \end{aligned}$$
(3.4)

Due to the locally Lipschitzian condition on f_1, f_2 , it is possible to choose $t^0 = (t_1^0, t_2^0) < 0$ such that

$$f_1(x,\overline{u},\overline{v}) - f_1(x,0,0) + t_1^0 \sin x \le 0,$$

$$f_2(x,\overline{u},\overline{v}) - f_2(x,0,0) + t_2^0 \sin x \le 0.$$

Hence, from these inequalities and the system (3.4), for all $t \leq t^0$, $W^{t^0} = (\overline{u}, \overline{v})$ is a supersolution for (1.5).

Lemma 3.6. Let (H4), (H5) hold. Then for a given h_1, h_2 , there exists an unbounded domain \Re in the plane such that if $t \in \Re$, system (1.5) has no supersolution.

Proof. Suppose W = (u, v) is a supersolution for (1.5). Multiplying both equations of this system by $\sin x$, integration them by parts and using (2.3), (2.6) we deduce that

$$(\underline{A} - I) \begin{pmatrix} \rho_1 \\ \rho_2 \end{pmatrix} \le \frac{\pi}{2} \begin{pmatrix} -s_1 \\ -s_2 \end{pmatrix}, \tag{3.5}$$

$$\left(\overline{A} - I\right) \begin{pmatrix} \rho_1\\ \rho_2 \end{pmatrix} \le \frac{\pi}{2} \begin{pmatrix} -s_1\\ -s_2 \end{pmatrix}.$$
(3.6)

Where $\rho_1 = \int_0^{\pi} u \sin x$, $\rho_2 = \int_0^{\pi} v \sin x$, $s_1 = t_1 - c$, $s_2 = t_2 - c$ and c is the constant in (2.3) and (2.6). From remark 2.1, applying $(\underline{A} - I)^{-1}$ and $(\overline{A} - I)^{-1}$ to (3.5) and (3.6), respectively, we obtain that

- (i) If $\rho_1 \leq 0$, then $s_2 \leq \frac{\underline{d}-1}{\underline{b}}s_1$ when $\underline{b} \neq 0$, or $s_1 \leq 0$ when $\underline{b} = 0$. (ii) If $\rho_1 \geq 0$, then $s_2 \leq \frac{\overline{d}-1}{\overline{b}}s_1$ when $\overline{b} \neq 0$, or $s_1 \leq 0$ when $\overline{b} = 0$.

Therefore, independently of the sign of ρ_1 , the pair (s_1, s_2) is in a region composed of the union of two half-planes passing through the origin, each of them bounded above by a straight-line of negative or infinity slope. \Re is the complement of this region in the original variables t_1 and t_2 .

Now, we are at a position to prove the Ambrosetti-Prodi type result for system (1.5).

Theorem 3.7. Suppose that conditions (H1)–(H5) are satisfied and that there exists a matrix

$$A(x) = \begin{pmatrix} a(x) & b(x) \\ c(x) & d(x) \end{pmatrix},$$

with $b(x), c(x) \geq 0$ (cooperativeness condition on A(x)) satisfies (2.5) such that

$$F(x,\xi) - F(x,\eta) \ge A(x)(\xi - \eta), \quad \text{for } \xi, \eta \in \mathbb{R}^2, \ \xi \ge \eta.$$
(3.7)

Then there exists a continuous curve Γ splitting \mathbb{R}^2 into two unbounded components N and E such that:

- (1) for each $t = (t_1, t_2) \in N$, (1.5) has no solution;
- (2) for each $t = (t_1, t_2) \in E$, (1.5) has at least two solutions.

Proof. For each $\theta \in \mathbb{R}$, define

$$L_{\theta} = \{ (t_1, t_2) \in \mathbb{R}^2; t_2 + \theta = t_1 \},\$$

and $R(\theta) = \{t_1 \in \mathbb{R}; (1.5) \text{ has a supersolution with } t \in L_{\theta} \text{ for some } t_2 \in \mathbb{R}\}.$ Lemmas 3.5 and 3.6 allows us to define the continuous curve

$$\Gamma(\theta) = (\sup R(\theta), \sup R(\theta) - \theta).$$

which splits the plane into two disjoints unbounded domains N and E such that for all $t \in N$ no supersolution exists for (1.5), while for all $t \in E$ (1.5) has a supersolution.

Obviously, for all $t \in N$, no solution exists for (1.5), result (1) is proved.

To prove result (2), now we use the abstract variational theorems to find the solutions of (1.5) when $t \in E$. We write

$$\langle J'(W), \Psi \rangle$$

= $\langle W, \Psi \rangle - \int_0^{\pi} [(f_1(x, u, v) + t_1 \sin x + h_1)\psi_1 + (f_2(x, u, v) + t_2 \sin x + h_2)\psi_2].$

Given $t \in E$ there exists a supersolution $W^t = (u^t, v^t)$ and a subsolution $W_t =$ (u_t, v_t) of (1.5) such that $W_t \leq W^t$ in $(0, \pi)$. Let

$$M = [W_t, W^t] = \{ W \in X; W_t \le W \le W^t \}.$$

since $W_t, W^t \in L^\infty$ by assumption, also $M \subset L^\infty$ and $H(x, W(x)) + (t_1 \sin x + t_2)$ $h_1)u + (t_2 \sin x + h_2)v \le c$ for all $W \in M$ and almost every $x \in (0, \pi)$.

Clearly, M is a closed and convex subset of X, hence weakly closed. Since M is essentially bounded, $J(W) \geq \frac{1}{2} ||W||_X^2 - c$ is coercive on M. On the other hand, if

 $W_n \to W$ weakly in X, where $W_n, W \in M$, we may assume that $W_n \to W$ pointwise almost everywhere; moreover, $|H(x, W_n) + (t_1 \sin x + h_1)u_n + (t_2 \sin x + h_2)v_n| \leq c$ uniformly, using Lebesgue Dominated Convergence Theorem, we have

$$\int_0^{\pi} H(x, W_n) + \int_0^{\pi} \left[(t_1 \sin x + h_1)u_n + (t_2 \sin x + h_2)v_n \right]$$

$$\to \int_0^{\pi} H(x, W) + \int_0^{\pi} \left[(t_1 \sin x + h_1)u + (t_2 \sin x + h_2)v \right].$$

Hence J is weakly lower semi-continuous on M. Then we can use [17, Theorem 1.2] to find a vector function $W_0 = (u_0, v_0) \in X$ such that $W_0 \in M$ is the infimum of the functional J restricted to M.

To see that W_0 is a weak solution of (1.5), for $\varphi = (\varphi_1, \varphi_2) \in C_0^{\infty}(0, \pi)$ and $\varepsilon > 0$ let

$$u_{\varepsilon} = \min\{u^{t}, \max\{u_{t}, u_{0} + \varepsilon\varphi_{1}\}\} = u_{0} + \varepsilon\varphi_{1} - \varphi_{1}^{\varepsilon} + \varphi_{1\varepsilon}$$
$$v_{\varepsilon} = \min\{v^{t}, \max\{v_{t}, v_{0} + \varepsilon\varphi_{2}\}\} = v_{0} + \varepsilon\varphi_{2} - \varphi_{2}^{\varepsilon} + \varphi_{2\varepsilon}$$

with

$$\begin{aligned} \varphi_1^{\varepsilon} &= \max\{0, u_0 + \varepsilon \varphi_1 - u^t\} \ge 0, \\ \varphi_2^{\varepsilon} &= \max\{0, v_0 + \varepsilon \varphi_2 - v^t\} \ge 0, \end{aligned}$$

and

$$\varphi_{1\varepsilon} = -\min\{0, u_0 + \varepsilon \varphi_1 - u_t\} \ge 0,$$

$$\varphi_{2\varepsilon} = -\min\{0, v_0 + \varepsilon \varphi_2 - v_t\} \ge 0.$$

Note that $W_{\varepsilon} = (u_{\varepsilon}, v_{\varepsilon}) \in M$ and $\varphi^{\varepsilon} = (\varphi_1^{\varepsilon}, \varphi_2^{\varepsilon}), \varphi_{\varepsilon} = (\varphi_{1\varepsilon}, \varphi_{2\varepsilon}) \in X \cap L^{\infty}(0, \pi).$

The functional J is differentiable in direction $W_{\varepsilon} - W_0$. Since W_0 minimizes J in M we have

$$0 \leq \langle W_{\varepsilon} - W_0, J'(W_0) \rangle = \varepsilon \langle \varphi, J'(W_0) \rangle - \langle \varphi^{\varepsilon}, J'(W_0) \rangle + \langle \varphi_{\varepsilon}, J'(W_0) \rangle,$$

so that

$$\langle \varphi, J'(W_0) \rangle \ge \frac{1}{\varepsilon} [\langle \varphi^{\varepsilon}, J'(W_0) \rangle - \langle \varphi_{\varepsilon}, J'(W_0) \rangle].$$

Now, from W^t is a supersolution to (1.5), we get

$$\begin{aligned} \langle \varphi^{\varepsilon}, J'(W_0) \rangle \\ &= \langle \varphi^{\varepsilon}, J'(W^t) \rangle + \langle \varphi^{\varepsilon}, J'(W_0) - J'(W^t) \rangle \\ &\geq \langle \varphi^{\varepsilon}, J'(W_0) - J'(W^t) \rangle \\ &= \int_{\Omega} [(u_0 - u^t)'(u_0 + \varepsilon \varphi_1 - u^t)' + (v_0 - v^t)''(v_0 + \varepsilon \varphi_2 - v^t)''] \\ &- \int_{\Omega} [f_1(x, W_0) - f_1(x, W^t)](u_0 + \varepsilon \varphi_1 - u^t) \\ &- \int_{\Omega} [f_2(x, W_0) - f_2(x, W^t)](v_0 + \varepsilon \varphi_2 - v^t) \\ &\geq \varepsilon \int_{\Omega} [(u_0 - u^t)'\varphi_1' + (v_0 - v^t)''\varphi_2''] \\ &- \varepsilon \int_{\Omega} |f_1(x, W_0) - f_1(x, W^t)||\varphi_1| - \varepsilon \int_{\Omega} |f_2(x, W_0) - f_2(x, W^t)||\varphi_2| \end{aligned}$$

where $\Omega = \{x \in (0, \pi); W_0(x) + \varepsilon \varphi(x) \ge W^t(x) > W_0(x)\}$. Note that meas $(\Omega) \to 0$ as $\varepsilon \to 0$. Hence by absolute continuity of the Lebesgue integral we obtain that

$$\langle \varphi^{\varepsilon}, J'(W_0) \rangle \ge o(\varepsilon)$$

where $o(\varepsilon)/\varepsilon \to 0$ as $\varepsilon \to 0$. Similarly, we conclude that $\langle \varphi_{\varepsilon}, J'(W_0) \rangle \leq o(\varepsilon)$; thus $\langle \varphi, J'(W_0) \rangle \geq 0$

for all $\varphi \in C_0^{\infty}(0,\pi)$. Reversing the sign of φ and since $C_0^{\infty}(0,\pi)$ is dense in X we finally get that $J'(W_0) = 0$, i.e. W_0 is a weak solution to (1.5). Then using (3.7) and a Maximum Principle Lemma 3.2, we claim that W_0 is a local minimum of J.

Suppose by contradiction that W_0 is not a local minimum, then for every $\varepsilon > 0$ there is $\widetilde{W_{\varepsilon}} \in \overline{B_{\varepsilon}(W_0)}$ (a ball of radius ε around $W_0 \in X$) such that $J(\widetilde{W_{\varepsilon}}) < J(W_0)$. We know that $\overline{B_{\varepsilon}(W_0)}$ is weaker sequentially compact in X and J is weakly lower semi-continuous, therefore there is $\widehat{W_{\varepsilon}} \in \overline{B_{\varepsilon}(W_0)}$ such that

$$J(\widehat{W}_{\varepsilon}) = \inf_{\overline{B_{\varepsilon}(W_0)}} J \le J(\widetilde{W}_{\varepsilon}) < J(W_0),$$

and $\langle J'(\widehat{W_{\varepsilon}}), \widehat{W_{\varepsilon}} - W_0 \rangle \leq 0$, or

$$J'(\widehat{W}_{\varepsilon}) = \lambda_{\varepsilon}(\widehat{W}_{\varepsilon} - W_0) \quad \text{with } \lambda_{\varepsilon} \le 0,$$

namely

$$\int_{0}^{\pi} (\widehat{u_{\varepsilon}}' \psi_{1}' + \widehat{v_{\varepsilon}}'' \psi_{2}'') - \int_{0}^{\pi} [f_{1}(x, \widehat{u_{\varepsilon}}, \widehat{v_{\varepsilon}})\psi_{1} + f_{2}(x, \widehat{u_{\varepsilon}}, \widehat{v_{\varepsilon}})\psi_{2}] - \int_{0}^{\pi} [(t_{1}\sin x + h_{1})\psi_{1} + (t_{2}\sin x + h_{2})\psi_{2}] = \lambda_{\varepsilon} [(\widehat{u_{\varepsilon}} - u_{0})\psi_{1} + (\widehat{v_{\varepsilon}} - v_{0})\psi_{2}].$$

$$(3.8)$$

On the other hand, from Definition 3.1 we have

$$\int_{0}^{\pi} (u_{t}'\psi_{1}' + v_{t}''\psi_{2}'') - \int_{0}^{\pi} [f_{1}(x, u_{t}, v_{t})\psi_{1} + f_{2}(x, u_{t}, v_{t})\psi_{2}] - \int_{0}^{\pi} [(t_{1}\sin x + h_{1})\psi_{1} + (t_{2}\sin x + h_{2})\psi_{2}] \le 0,$$
(3.9)

and

$$\int_{0}^{\pi} (u^{t'}\psi_{1}' + v^{t''}\psi_{2}'') - \int_{0}^{\pi} [f_{1}(x, u^{t}, v^{t})\psi_{1} + f_{2}(x, u^{t}, v^{t})\psi_{2}] - \int_{0}^{\pi} [(t_{1}\sin x + h_{1})\psi_{1} + (t_{2}\sin x + h_{2})\psi_{2}] \ge 0.$$
(3.10)

From (3.8)–(3.9), we obtain

$$\int_0^{\pi} [(\widehat{u_{\varepsilon}}' - u_t')\psi_1' + (\widehat{v_{\varepsilon}}'' - v_t'')\psi_2''] \\ - \int_0^{\pi} [(f_1(x,\widehat{W_{\varepsilon}}) - f_1(x,W_t))\psi_1 + (f_2(x,\widehat{W_{\varepsilon}}) - f_2(x,W_t))\psi_2] \\ \ge \lambda_{\varepsilon} [(\widehat{u_{\varepsilon}} - u_t + u_t - u_0)\psi_1 + (\widehat{v_{\varepsilon}} - v_t + v_t - v_0)\psi_2].$$

This implies

$$-(\widehat{u_{\varepsilon}}-u_{t})'' \geq f_{1}(x,\widehat{W_{\varepsilon}}) - f_{1}(x,W_{t}) + \lambda_{\varepsilon}(\widehat{u_{\varepsilon}}-u_{t}) + \lambda_{\varepsilon}(u_{t}-u_{0}),$$
$$(\widehat{v_{\varepsilon}}-v_{t})^{(4)} \geq f_{2}(x,\widehat{W_{\varepsilon}}) - f_{2}(x,W_{t}) + \lambda_{\varepsilon}(\widehat{v_{\varepsilon}}-v_{t}) + \lambda_{\varepsilon}(v_{t}-v_{0}).$$

Then from (3.7) we obtain

$$\begin{pmatrix} -(\widehat{u_{\varepsilon}} - u_t)''\\ (\widehat{v_{\varepsilon}} - v_t)^{(4)} \end{pmatrix} \ge A(x)(\widehat{W_{\varepsilon}} - W_t) + \lambda_{\varepsilon}(\widehat{W_{\varepsilon}} - W_t),$$

note that $\lambda_{\varepsilon} \leq 0$, and by using Lemma 3.2 we obtain

$$W_{\varepsilon} - W_t \ge 0$$
, or $W_t \le W_{\varepsilon}$.

Similarly, from (3.10)-(3.8), we can obtain

$$\widehat{W}_{\varepsilon} \leq W^t$$
.

Which contradicts $J(W_0) = \inf_M J(W)$.

Finally, since J is not bounded from below, a weaker form of the Mountain Pass Theorem can be used to find another solution $W_1 \neq W_0$ of (1.5). Then result (2) is proved.

4. Example: A piecewise linear problem

Consider the system

$$-u'' = k_1 u^+ + \epsilon v^+ + t_1 \sin x + h_1(x), \quad \text{in } (0, \pi),$$

$$v^{(4)} = \epsilon u^+ + k_2 v^+ + t_2 \sin x + h_2(x), \quad \text{in } (0, \pi),$$

$$u(0) = u(\pi) = 0,$$

$$v(0) = v(\pi) = v''(0) = v''(\pi) = 0.$$

(4.1)

Where ϵ and k_1, k_2 are constants, t_1, t_2 are parameters and $h_1, h_2 \in C[0, \pi]$ are fixed functions with $\int_0^{\pi} h_1 \sin x = \int_0^{\pi} h_2 \sin x = 0$. This problem is similar to system (1.4).

Theorem 4.1. Suppose that $k_1 > 1$, $k_2 > 1$ and $\epsilon \ge 0$. Then there exists a curve Γ splitting \mathbb{R}^2 into two unbounded components N and E such that:

- (1) for each $t = (t_1, t_2) \in N$, (4.1) has no solution;
- (2) for each $t = (t_1, t_2) \in E$, (4.1) has at least two solutions.

Proof. Let

$$\overline{A} = \begin{pmatrix} k_1 & 0\\ 0 & k_2 \end{pmatrix}, \quad \underline{A} = \begin{pmatrix} 0 & 0\\ 0 & 0 \end{pmatrix}.$$

Then we can easily verify that the conditions of Theorem 3.7 hold and therefore the results are follow. $\hfill \Box$

Remark 4.2. (1) Denote by μ_i (i = 1, 2) the eigenvalues of matrix

$$A = \begin{pmatrix} k_1 & \epsilon \\ \epsilon & k_2 \end{pmatrix}$$

and let $\mu_1 \leq \mu_2$. It can be shown that $\mu_2 > 1$ since $k_1 > 1$ and $k_2 > 1$.

(2) This result gives a partial answer to Question 1 and Question 2 that were posted in [16] and stated in Section 1.

References

- A. C. Lazer, P. J. McKenna; Large-amplitude periodic oscillations in suspension bridge: some new connections with nonlinear analysis, SIAM Rev. 32 (1990) 537-578.
- [2] P. J. McKenna and W. Walter; Nonlinear oscillation in a suspension bridge, Arch. Rational Mech. Anal. 98 (1987) 167-177.
- [3] Q. H. Choi, T. Jung and P. J. McKenna; The study of a nonlinear suspension bridge equation by a variational reduction method, Appl. Anal. 50 (1995) 71-90.
- [4] Q. H. Choi and T. Jung; A nonlinear suspension bridge equation with nonconstant load, Nonli.Anal. 35 (1999) 649-668.
- [5] Y. K. An and C. K. Zhong; Periodic solutions of Nonlinear suspension bridge equation with damping and nonconstant load, J. Math. Anal. Appl. 279 (2003) 569-579.
- [6] A. Ambrosetti, G. Prodi; On the inversion of some differentiable mappings with singularities between Banach spaces, Annali Mat. pura appl. 93 (1972) 231-246.
- [7] D. G. de Figueiredo; Lectures on boundary value problems of Ambrosetti-Prodi type, 12th Brazilian Seminar of Analysis, São Paulo, Brazil (1980).
- [8] D. G. de Figueiredo; On the superlinear Ambrosetti-Prodi problem, MRC Tech Rep # 2522, May(1983).
- D. C. de Morais Filho; A variational approach to an Ambrosetti-Prodi type problem for a system of elliptic equations, Nonlinear Anal. TMA 26 (1996) 1655-1668.
- [10] D. C. de Morais Filho, F.R. Pereira, Critical Ambrosetti-Prodi type results for systems of Elliptic Equations, Nonlinear Anal. TMA, in prees.
- [11] K. C. Chang; Ambrosetti-Pfodi type results in elliptic systems, Nonlinear Anal. 51 (2002) 553-566.
- [12] P. Drabek, H. Leinfelder and G. Tajcova; Coupled string-beam equations as a model of suspension bridges, Appl. Math. 44 (1999) 97-142.
- [13] Y. K. An; Nonlinear Perturbations of a Coupled System of Steady State Suspension Bridge Equations, Nonli. Anal. 51 (2002) 1285-1292.
- [14] Y. K. An, X. L. Fan; On the coupled systems of second and fourth order elliptic equations, Appl. Math. Comput. 140 (2003) 341-351.
- [15] Y.K. An; Mountain pass solutions for the coupled systems of second and fourth order elliptic equations, Nonli. Anal. 63 (2005) 1034-1041.
- [16] F. Dalbono, P. J. McKenna; Multiplicity results for a class of asymmetric weakly coupled systems of second-order ordinary differential equations, Boundary Value Problems. 2 (2005) 129-151.
- [17] M. Struwe; Variational Methods, Springer-Verlag, 2000.

Yukun An

DEPARTMENT OF MATHEMATICS, NANJING UNIVERSITY OF AERONAUTICS AND ASTRONAUTICS, NANJING, 210016, CHINA

E-mail address: anyksd@hotmail.com

JING FENG

DEPARTMENT OF MATHEMATICS, NANJING UNIVERSITY OF AERONAUTICS AND ASTRONAUTICS, NANJING, 210016, CHINA

E-mail address: erma19831@sina.com